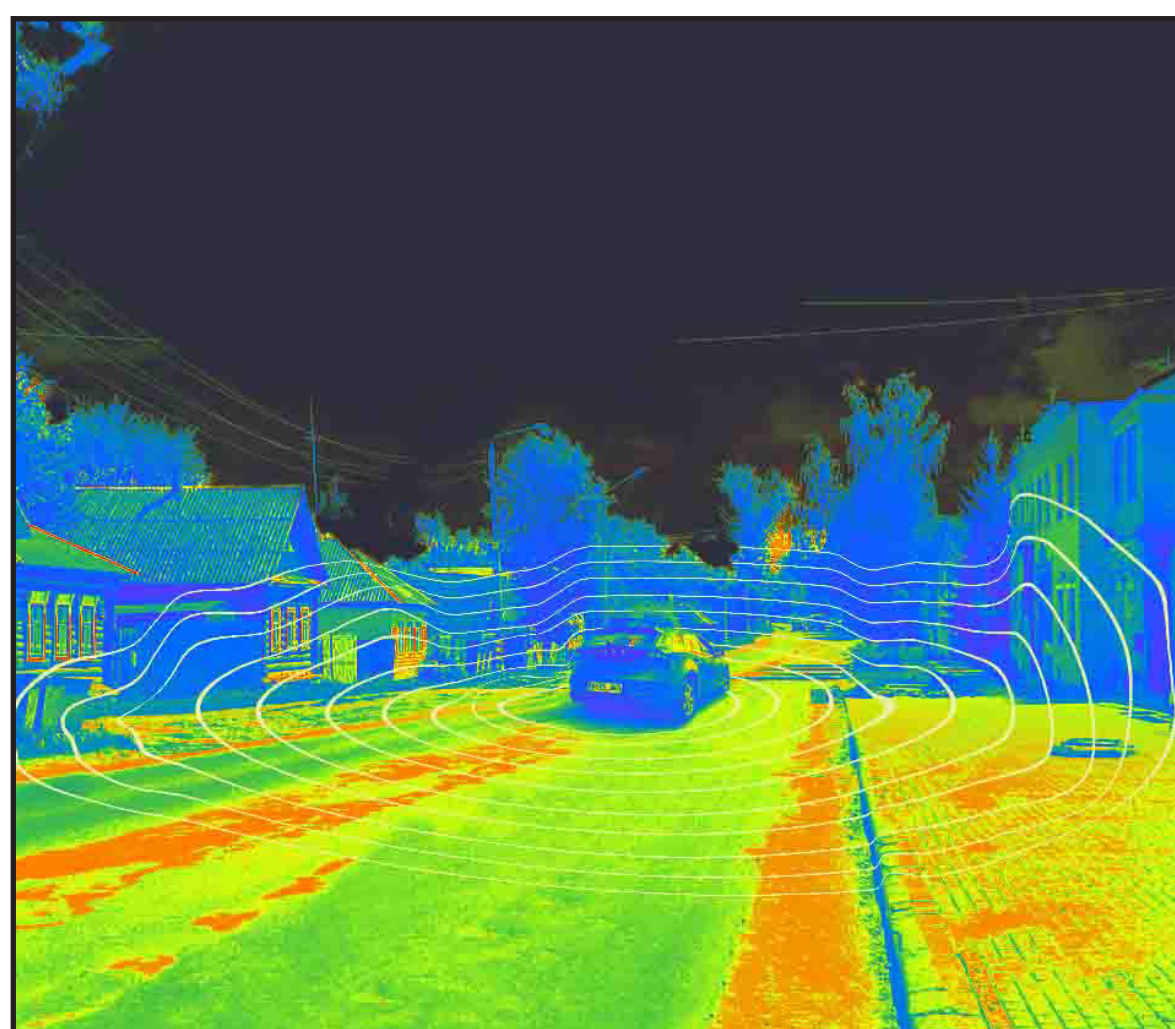


WHERE ARE YOU ON THE COMPLEXITY MATRIX?



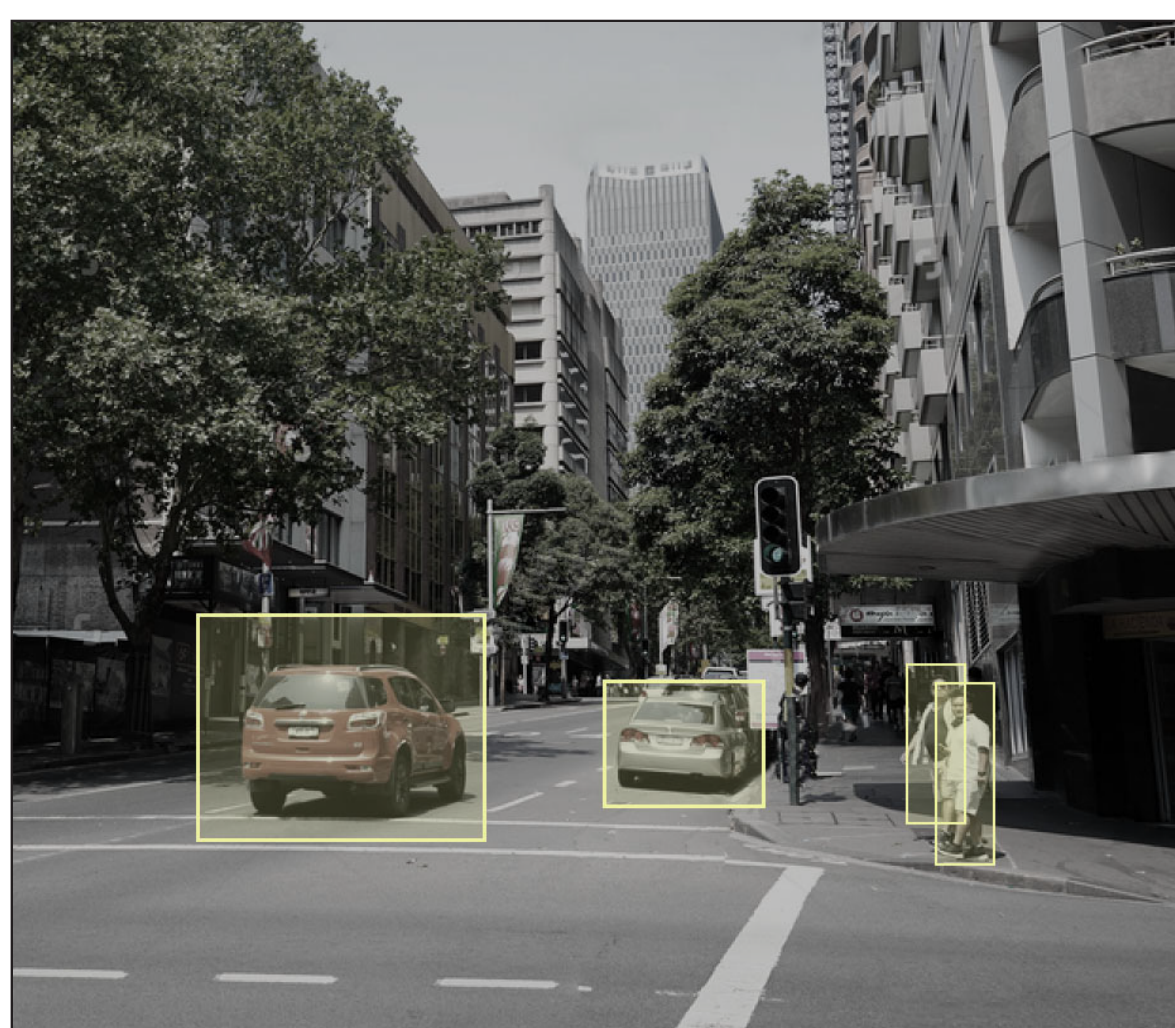
MultiSensor Fusion (+30 Mins/task)

Combining LiDAR and images from multiple angles captured from different sensors to reduce uncertainty in navigation.



LiDAR (+30 Mins/task)

Labeling images and videos in 360 degree visibility enabling vehicles to calculate the exact distance between objects.



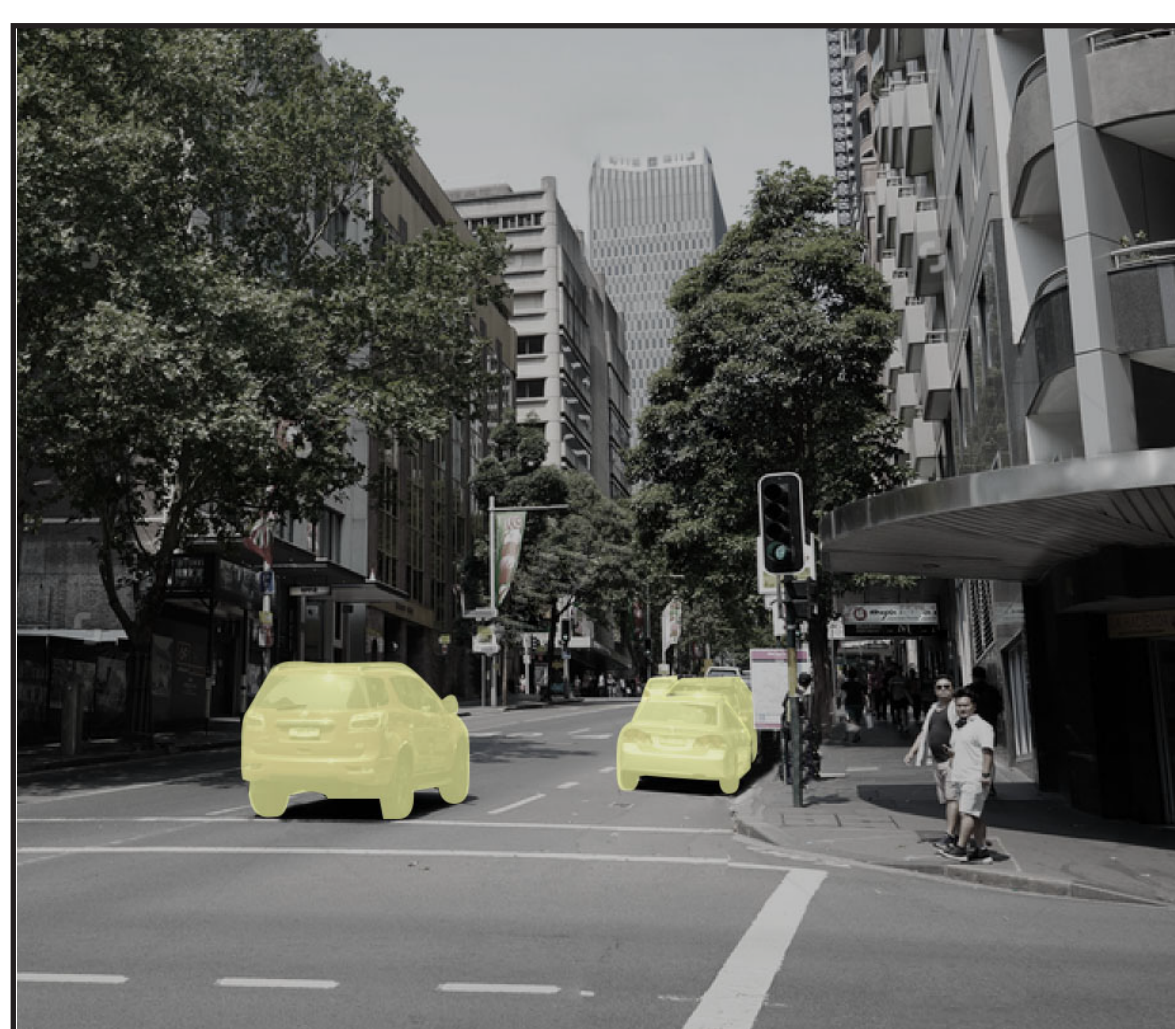
Tracking (+30 Mins/task)

Vehicle, face or pedestrian detection and tracking across frames of video, including occluded sections.



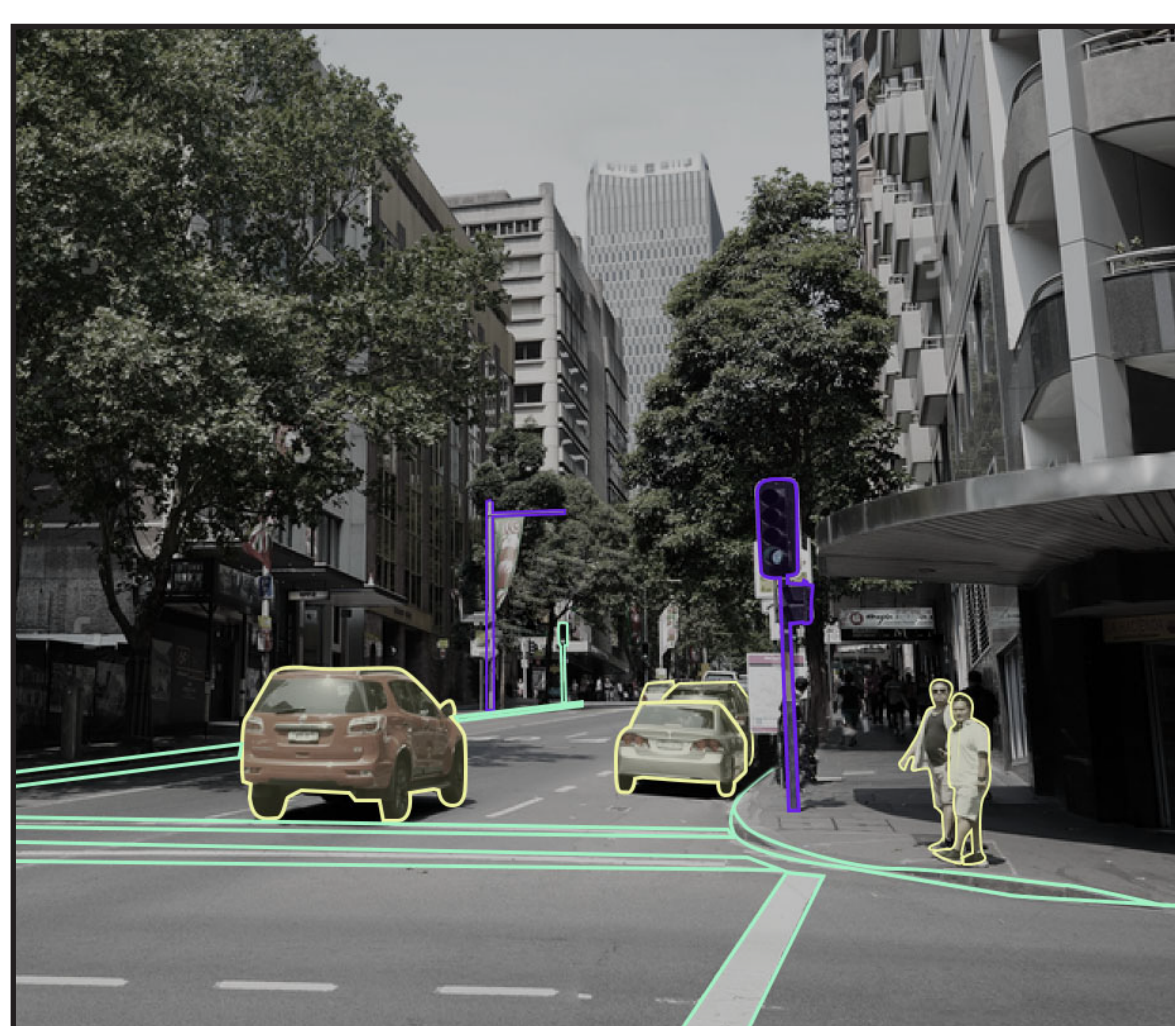
PanOptic Segmentation (+30 Mins/task)

Marking all objects precisely & differentiating them by class of object (car, tree, fire hydrant etc.)



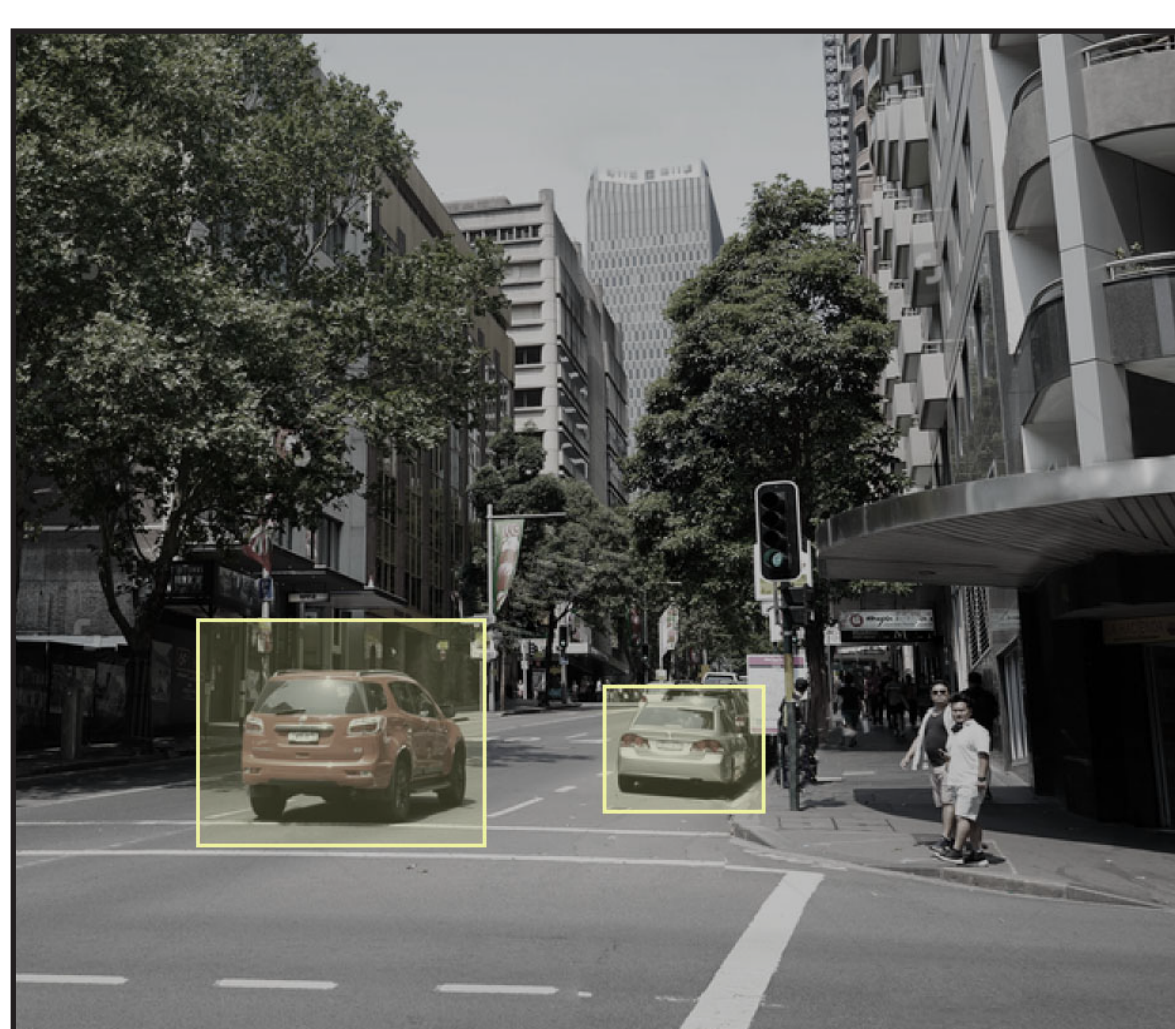
Segmentation (+30 Mins/task)

Marking boundaries around all objects in an image precisely to power driving of autonomous vehicles.



Polygons (Mins/task)

Marking location by drawing boundaries around desired objects such as vehicles, pedestrians, street lamps.



Bounding Boxes (Secs/task)

Drawing simple boxes around vehicles, pedestrians or animals for object localization for self driving vehicles.